Prof. Mark D Shattuck Physics 39907 Computational Physics October 17, 2024

Problem Set 5

Question 1. 2×2 Matrices: Find explicit examples of 2×2 matrices with the following properties.

- (1) $A^2 = -I$ for A with all real entries.
- (2) $P^2 = I$ for $P \neq I$.
- (3) LU = UL for U upper- and L lower-triangular.
- (4) $LU \neq UL$ for U upper- and L lower-triangular.
- (5) BC = -CB for $BC \neq 0$.
- (6) $D^2 = 0$ with all elements of D are non-zero.

Question 2. LDU factorization: Find the values of w, x, y, z such that:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = LDU = \begin{bmatrix} 1 & 0 \\ w & 1 \end{bmatrix} \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \begin{bmatrix} 1 & z \\ 0 & 1 \end{bmatrix}$$

- (1) Can all matrices A be decomposed this way? What are the conditions on a, b, c, d for this decomposition to work (or not work)?
- (2) Assuming the decomposition exists, what are the conditions on w, x, y, z for A^{-1} to exist?
- (3) Show that:

$$A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

- (4) What is the condition on A for the inverse to exist? How does it compare with the conditions on w, x, y, z above?
- (5) MATLAB has a function [L, U] = lu(A) that returns the LU decomposition. Make a new MATLAB function that returns the A = LDU decomposition: [L, D, U] = ldu(A). Here is a start:

```
1 function [L,D,U]=ldu(A)
2 % ldu <LDU decomposition of a matrix.>
3 % Usage:: [L,D,U]=ldu(A)
4 %
5
6 % revision history:
7 % 10/26/2023 Mark D. Shattuck <mds> ldu.m
8
9 %% Main
10 [L,U]=lu(A);
11 D=???
12 U=???
```

(6) Not all matrices A can be decomposed into A = LDU, where L is lower triangular. However, there is always a permutation of A which can be factored. So there is a always a permutation matrix P, a lower-triangular matrix L and an upper-triangular matrix U such that PA = LU. Further there is a unique factorization if the all of the diagonals of L are 1. Notice that $P^2 = I$ and so A = PLU.

So the MATLAB command [L,U]=lu(A) actually returns L=PL. Show that:

 $\begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix}$

does not have an LU decomposition and find its PLU decomposition and its PLDU decomposition.

Question 3. Linear Equations: Find the linear combination of these 3 vectors:

$$u_1 = \begin{bmatrix} 4\\1\\3 \end{bmatrix}, u_2 = \begin{bmatrix} 2\\-4\\9 \end{bmatrix}, u_3 = \begin{bmatrix} -1\\-2\\3 \end{bmatrix}$$

which gives

$$b = \begin{bmatrix} -2\\2\\9 \end{bmatrix}.$$

Question 4. Energy in a spring system: Consider a 3 mass 4 spring system with fixed-fixed boundaries separated by 1:

$$f_{1} \downarrow \qquad \boxed{M_{1}} - u_{1}$$

$$f_{2} \downarrow \qquad \boxed{M_{2}} - u_{2}$$

$$f_{3} \downarrow \qquad \boxed{M_{3}} - u_{3}$$

In class, we found the matrix representation of this system:

$$e = \Delta u,$$

$$T = Ce,$$

$$f = \Delta^T T.$$

- (1) What are the sizes of each matrix e, Δ, u, T, C, f ?
- (2) Assuming the applied forces are constant, write the total work done on the system for a displacement of

$$u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

directly in components and in matrix notation.

- (3) Find the change in potential energy of the springs for the same displacement u in both component form and matrix form.
- (4) Use the work-energy theorem to find the total potential energy of the system after a displacement u with forces f.
- (5) Show that the minimum potential energy corresponds to the force balance solution we derived in class.
- (6) Find and plot the displacements for the case that $c_m = 1 + m/2$, with masses $M_n = N n$, where N = 4, n=1:N-1, m=1:N for the case shown and the forces are from gravity i.e., $f_n = M_n g$ and g = 1. You can plot the displacements against n.
- (7) Find the solution for N = 20.